

Linear vector space over complex field

① Vector space.

$$\psi \equiv (x_1, x_2, \dots, x_n)$$

- x_i are ordered
- x_i are complex

$$(i) \quad \psi + \phi = (x_1 + y_1, x_2 + y_2, \dots, x_n + y_n)$$

$$(ii) \quad (\psi_1 + \psi_2) + \psi_3 = \psi_1 + (\psi_2 + \psi_3)$$

$$(iii) \quad \psi + 0 = \psi$$

$$(iv) \quad \psi + (-\psi) = 0$$

vector addition

$$(i) \quad \lambda \psi = (\lambda x_1, \lambda x_2, \dots, \lambda x_n)$$

$$(ii) \quad \lambda \cdot 1 \cdot \psi = \lambda \psi \quad \text{and} \quad \lambda \frac{1}{\lambda} \psi = 1 \psi$$

$$(iii) \quad \lambda (\psi + \phi) = \lambda \psi + \lambda \phi$$

$$(iv) \quad (\lambda_1 + \lambda_2) \psi = \lambda_1 \psi + \lambda_2 \psi$$

scalar multiplication

② One can introduce base vector

$$e_1 = (1, 0, \dots, 0)$$

$$e_2 = (0, 1, \dots, 0)$$

$\vdots$

$$e_n = (0, 0, \dots, 1)$$

$$\rightarrow (e_i, e_j) = \delta_{ij}$$

orthonormal basis set

$$\rightarrow \text{Summation convention}$$

$$\begin{aligned} \psi &= e_1 x_1 + e_2 x_2 + \dots + e_n x_n \\ &= \sum_{i=1}^n e_i x_i \equiv e_i x_i \end{aligned}$$

③ Scalar product

One could define a scalar product on a vector space.

Properties of scalar product:

- (i) $(\phi, \psi) = (\psi, \phi)^*$
- (ii) $(\phi, \lambda \psi) = \lambda (\phi, \psi) \Rightarrow (\lambda \phi, \psi) = \lambda^* (\phi, \psi)$
- (iii) $(\phi, \psi + \psi_2) = (\phi, \psi) + (\phi, \psi_2)$
- (iv) $(e_i, e_j) = \delta_{ij}$

④ Notes:

→ Using ③ (i) we have

$$\begin{aligned} \rightarrow (\phi, \psi) &= (e_i x_i, e_j y_j) \\ &= x_i^* y_j (e_i, e_j) \\ &= x_i^* y_j \delta_{ij} \\ &= x_i^* y_i \end{aligned}$$

$$(\psi, \psi) = (\psi, \psi)^* = \text{real.}$$

$$\begin{aligned} \phi &= e_i x_i \\ \psi &= e_j y_j \end{aligned}$$

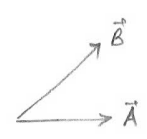
→ This is a generalization of the scalar product of two vectors in Euclidean vector space.

$$\vec{A} \cdot \vec{B} = a_i b_i$$

$$\rightarrow (\psi, \psi) = x_i^* x_i = \sum_i |x_i|^2 \geq 0$$

$$\rightarrow (\psi, \psi) = 0 \Rightarrow \psi = 0$$

⑤ Schwarz's inequality :



$$\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos \theta$$
$$\frac{(\vec{A} \cdot \vec{B})^2}{(\vec{A} \cdot \vec{A})(\vec{B} \cdot \vec{B})} = \cos^2 \theta \leq 1$$

(iii)

Let $\alpha = \lambda \psi + \mu \phi$

$$(\alpha, \alpha) = (\lambda \psi + \mu \phi, \lambda \psi + \mu \phi)$$
$$= |\lambda|^2 (\psi, \psi) + \lambda^* \mu (\psi, \phi) + \lambda \mu^* (\phi, \psi) + |\mu|^2 (\phi, \phi)$$

For what λ is (α, α) minimised?

$$\frac{\partial}{\partial \lambda} (\alpha, \alpha) = \lambda^* (\psi, \psi) + \mu^* (\phi, \psi)$$
$$\frac{\partial}{\partial \lambda^*} (\alpha, \alpha) = \lambda (\psi, \psi) + \mu (\phi, \psi)$$
$$= [\lambda^* (\psi, \psi) + \mu^* (\phi, \psi)]^* = \left[\frac{\partial}{\partial \lambda} (\alpha, \alpha) \right]^*$$
$$\frac{\partial}{\partial \mu} (\alpha, \alpha) = \lambda^* (\psi, \phi) + \mu^* (\phi, \phi) = \left[\frac{\partial}{\partial \mu^*} (\alpha, \alpha) \right]^*$$

Setting $\frac{\partial}{\partial \lambda^*} (\alpha, \alpha) = 0 \Rightarrow \lambda (\psi, \psi) = -\mu (\phi, \psi)$ — (i)

$$\Rightarrow \lambda = -\mu \frac{(\phi, \psi)}{(\psi, \psi)}$$
$$\Rightarrow \lambda^* = -\mu^* \frac{(\phi, \psi)}{(\psi, \psi)}$$
 — (ii)

Using (i) and (ii) in (iii)

$$(\alpha, \alpha) = \mu \mu^* \frac{(\psi, \phi)}{(\psi, \psi)} \frac{(\phi, \psi)}{(\psi, \psi)} - \mu \mu^* \frac{|(\psi, \phi)|^2}{(\psi, \psi)} + \mu \mu^* (\phi, \phi)$$
$$= \mu \mu^* \left[(\phi, \phi) - \frac{|(\psi, \phi)|^2}{(\psi, \psi)} \right]$$

Since $(\alpha, \alpha) \geq 0$ we have

$$\frac{|(\psi, \phi)|^2}{(\psi, \psi)(\phi, \phi)} \leq 1$$

⑥ We can define an angle.

$$\cos^2 \theta = \frac{|\langle \psi, \phi \rangle|^2}{(\psi, \psi)(\phi, \phi)} \leq 1$$

$$\cos \theta \Big|_{\psi, \phi} = 1 \Rightarrow \psi \text{ and } \phi \text{ are in the same direction.}$$

$$\psi = a \phi$$

$$\cos \theta \Big|_{\psi, \phi} = 0 \Rightarrow \psi \text{ and } \phi \text{ are orthogonal.}$$

⑦ Change of base vectors

$$\psi = e_i x_i$$

$$\psi = e'_i x'_i$$

$$(e_i, e_j) = \delta_{ij} \rightarrow \text{orthonormal basis}$$

$$(e'_i, e'_j) = \delta_{ij}$$

$$\text{Let } e_i = s_{ij} e'_j$$

$$\text{clearly } (e'_j, e_i) = (e'_j, s_{ik} e'_k) = s_{ij}$$

$$\Rightarrow s_{ij} \text{ are direction cosines between } e_i \text{ and } e'_j$$

$$(e_i, e_j) = (s_{im} e'_m, s_{jn} e'_n) = s_{im}^* s_{jn}$$

$$s^T = (s^T)^*$$

$$\Rightarrow s s^T = 1$$

$$\text{Similarly, } e'_i = s_{ij}^* e_j$$

$$\text{because } (e'_i, e_j) = (s_{ik}^* e_k, e_j) = s_{ij}$$

⑧ Thw, we have.

$$\vec{e} = \vec{S} \vec{e}'$$

$$\vec{e}' = \vec{S}^\dagger \vec{e}$$

⑨ Since

we have

$$S S^\dagger = I$$

$$(\det S) (\det S^\dagger) = 1$$

$$(\det S) (\det S^*) = 1$$

$$(\det S) (\det S)^* = 1$$

$$|(\det S)|^2 = 1$$

$$\therefore \det A = \det A^T$$

⑩

$$(\psi, \phi) = (e_i x_i, e_j y_j) = x_i^* y_i$$

$$= x_i^* y_j (e_i, e_j)$$

$$= x_i^* y_j (S_{im} e'_m, S_{jn} e'_n)$$

$$= x_i^* y_j S_{im}^* S_{jn} \delta_{mn}$$

$$= x_i^* y_j S_{jm} S_{mi}^\dagger$$

$$= x_i^* y_i \quad \checkmark$$