

# Final Exam (Spring 2018)

## PHYS 510: Classical Mechanics

Date: 2018 May 11

1. (20 points.) A pendulum consists of a mass  $m_2$  hanging from a pivot by a massless string of length  $a$ . The pivot, in general, has mass  $m_1$ , but, for simplification let  $m_1 = 0$ . Let the pivot be constrained to move on a horizontal rod. See Figure 1. For simplification, and at loss of generality, let us chose the motion of the pendulum in a vertical plane containing the rod.

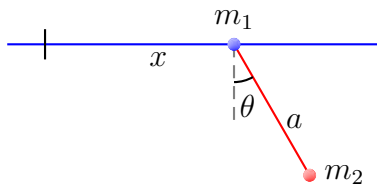


Figure 1: Problem 1.

- (a) Determine the Lagrangian for the system to be

$$L(x, \dot{x}, \theta, \dot{\theta}) = \frac{1}{2}m_2\dot{x}^2 + \frac{1}{2}m_2a^2\dot{\theta}^2 + m_2a\dot{x}\dot{\theta} \cos \theta + m_2ga \cos \theta. \quad (1)$$

- (b) Evaluate the following derivatives and give physical interpretations of each of these.

$$\frac{\partial L}{\partial \dot{x}} = m_2\dot{x} + m_2a\dot{\theta} \cos \theta, \quad (2a)$$

$$\frac{\partial L}{\partial x} = 0, \quad (2b)$$

$$\frac{\partial L}{\partial \dot{\theta}} = m_2a^2\dot{\theta} + m_2a\dot{x} \cos \theta, \quad (2c)$$

$$\frac{\partial L}{\partial \theta} = -m_2a\dot{x}\dot{\theta} \sin \theta - m_2ga \sin \theta. \quad (2d)$$

- (c) Determine the equations of motion for the system. Express them in the form

$$\ddot{x} + a\ddot{\theta} \cos \theta - a\dot{\theta}^2 \sin \theta = 0, \quad (3a)$$

$$a\ddot{\theta} + \ddot{x} \cos \theta + g \sin \theta = 0. \quad (3b)$$

Observe that, like in the case of simple pendulum, the motion is independent of the mass  $m_2$  when  $m_1 = 0$ .

(d) In the small angle approximation show that the equations of motion reduce to

$$\ddot{x} + a\ddot{\theta} = 0, \quad (4a)$$

$$a\ddot{\theta} + \ddot{x} + g\theta = 0. \quad (4b)$$

Determine the solution to be given by

$$\theta = 0 \quad \text{and} \quad \ddot{x} = 0. \quad (5)$$

Interpret this solution.

(e) The solution  $\theta = 0$  seems to be too restrictive. Will this system not allow  $\theta \neq 0$ ? To investigate this, let us not restrict to the small angle approximation. Rewrite Eqs. (3), using Eq. (3a) in Eq. (3b), as

$$\ddot{x} + a\ddot{\theta} \cos \theta - a\dot{\theta}^2 \sin \theta = 0, \quad (6a)$$

$$\sin \theta \left[ a\ddot{\theta} \sin \theta + a\dot{\theta}^2 \cos \theta + g \right] = 0. \quad (6b)$$

In this form we immediately observe that  $\theta = 0$  is a solution. However, it is not the only solution. Towards interpreting Eqs. (6) let us identify the coordinates of the center of mass of the  $m_1$ - $m_2$  system,

$$(m_1 + m_2)x_{\text{cm}} = m_1x + m_2(x + a \sin \theta), \quad (7a)$$

$$(m_1 + m_2)y_{\text{cm}} = -m_2a \cos \theta, \quad (7b)$$

which for  $m_1 = 0$  are the coordinates of the mass  $m_2$ ,

$$x_{\text{cm}} = x + a \sin \theta, \quad (8a)$$

$$y_{\text{cm}} = -a \cos \theta. \quad (8b)$$

Show that

$$\dot{x}_{\text{cm}} = \dot{x} + a\dot{\theta} \cos \theta, \quad (9a)$$

$$\dot{y}_{\text{cm}} = a\dot{\theta} \sin \theta, \quad (9b)$$

and

$$\ddot{x}_{\text{cm}} = \ddot{x} + a\ddot{\theta} \cos \theta - a\dot{\theta}^2 \sin \theta, \quad (10a)$$

$$\ddot{y}_{\text{cm}} = a\ddot{\theta} \sin \theta + a\dot{\theta}^2 \cos \theta. \quad (10b)$$

Comparing Eqs. (6) and Eqs. (10) we learn that

$$\ddot{x}_{\text{cm}} = 0, \quad (11a)$$

$$\sin \theta \left[ \ddot{y}_{\text{cm}} + g \right] = 0. \quad (11b)$$

Thus,  $\ddot{y}_{\text{cm}} = -g$  is the more general solution, and  $\theta = 0$  is a trivial solution.

- (f) Let us analyse the system for initial conditions:  $\theta(0) = \theta_0$ ,  $\dot{\theta}(0) = 0$ ,  $\dot{x}(0) = 0$ . Show that for this case  $\dot{x}_{\text{cm}}(0) = 0$  and

$$a(\cos \theta - \cos \theta_0) = \frac{1}{2}gt^2. \quad (12)$$

Plot  $\theta$  as a function of time  $t$ . Interpret this solution.

2. **(20 points.)** The path of a relativistic particle moving along a straight line with constant (proper) acceleration  $\alpha$  is described by the equation of a hyperbola

$$x^2 - c^2t^2 = x_0^2, \quad x_0 = \frac{c^2}{\alpha}. \quad (13)$$

This is the motion of a particle ‘dropped’ from  $x = x_0$  at  $t = 0$  in region of constant (proper) acceleration.

- (a) Will a photon dispatched to ‘chase’ this particle at  $t = 0$  from  $x = 0$  ever catch up with it? If yes, when and where does it catch up?
- (b) Will a photon dispatched to ‘chase’ this particle at  $t = 0$  from  $0 < x < x_0$  ever catch up with it? If yes, when and where does it catch up?
- (c) Will a photon dispatched to ‘chase’ this particle, at  $t = 0$  from  $x < 0$  ever catch up with it? If yes, when and where does it catch up?